

# **Operator Manual** Skydio QGC-Gov



**WARNING:** Please read all documentation provided with your Skydio X2D. For additional safety and operating resources and information visit: <u>Skydio.com/support</u>



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## **Overview**

Skydio QGC-Gov is an alternative application available for the Skydio Enterprise Controller for full flight control and access to X2D autonomy features. Skydio QGC-Gov enables the planning and automated execution of complex preplanned ground, structure and corridor survey missions using simple graphical tools. Images can be captured automatically using the color and thermal cameras, and at any time you can view the video feed, flight path and telemetry.

### **Safety Guidelines**



## **Overview**

## Flying Safely

#### **Pre-flight**

- · Ensure that all of the camera lenses are dust and smudge-free prior to flight
- · Inspect the battery magnets and connections for damage and debris prior to flight
- · Inspect propeller blades for nicks, cracks, or other visible damage prior to flight
- · Inspect the chassis for damage and debris prior to flight
- Ensure all 4 arms are fully deployed against the hard stops and arm clamps are fully seated prior to initiating flight. Failure to do so may result in unstable flight and/or a loss of control. A moderate amount of force is required to fully seat the clamp to the arm if the arm clamp closes with low effort, damage has occurred within the hinge and the drone should not be flown.

#### Environment

- Do not fly in precipitation, fog, or snow
- Fly with caution in low light, poor visibility, and nighttime conditions obstacle avoidance is disabled
- Do not fly in extremely hot temperatures above 109°F (43°C)
- Do not fly in extremely cold temperatures below 14°F (-10°C)
- When flying in temperatures below 32°F (0°C) ensure your batteries are pre-warmed to 50°F (10°C) prior to launch
- Avoid windy weather conditions, or gusts above 23 mph (37 km/h)
- Fly cautiously around reflective surfaces such as still water or mirrors
- · Before flying over water, ensure your drone has GPS lock. Launch and land your drone over a dry surface
- Avoid objects less than 0.5 in (1.27 cm) in diameter such as thin branches, utility lines, ropes, and netting
- Do not fly around objects in motion such as cars, boats, balls, animals, or other drones

#### Warnings

- Fly cautiously around people
- Avoid transparent or reflective surfaces, windows, or mirrors greater than 23 in (58 cm) wide
- Avoid moving obstacles, cars, and animals
- The pilot in command (PIC) is responsible for managing altitude, range, and battery level and monitoring in-app messages and alerts
- Avoid flight in low-light conditions
- Alert messages will display if Skydio X2 determines the environment is not safe for flight
- When instructed to do so, immediately fly Skydio X2 to the safest area and land
- · Flying at high altitudes may significantly increase the time required to return and safely land
- Propeller blades are sharp—handle with care
- · Skydio should not be used or handled by a person under the age of 18 years

#### Regulations

- Follow all civil aviation, such as the FAA or your countries regulatory agency, rules and regulations
- You are responsible for your Skydio X2 at all times, when operating your Skydio X2 check knowbeforeyoufly.org / B4UFLY / CASA-verified before flying.
- Do not fly in an environment where the use of the device is not authorized or restricted.
- Maintain visual line of sight at all times, unless you have received express permission to fly beyond visual line of sight from a civil aviation authority such as the FAA.



**INFO:** Visit https://skydio.com/safety and https://skydio.com/support for more information, helpful tips, videos, and articles.

### Launch QGC-Gov

- Step 1 Power on Skydio Enterprise Controller and X2D
- Step 2 Wait for the drone and controller to pair
- Step 3 Select the INFO menu

#### Step 4 - Select Launch Skydio QGC

• QGC-Gov will launch the Fly screen





## Overview

## Skydio Enterprise Controller

- 1. Left joystick
- 2. Right joystick
- 3. Menu/back button
- 4.D-pad
- 5. C1 button obstacle avoidance
- 6.C2 button toggle lights on/off
- 7. Return to Home button
- 8. Power button
- 9. Launch/Land button
- 10. Pause button
- 11. Controller clamshell
- 12. User interface screen
- 13. Reset button
- 14. Reset button (alternate)
- 15. R1 button shutter/record
- 16. L1 button boost
- 17. Right wheel zoom
- 18. Left wheel gimbal tilt
- 19. R2 button toggle map
- **20.** L2 button toggle thermal to color
- 21. USB-C port
- 22. Cooling fan

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23. Neck-strap and tripod (1/4-20) mount





**CAUTION:** Skydio Enterprise Controller is not weatherproof. Do not operate in any precipitation, including rain, fog, snow, or similar environments. Do not rest the controller in sand, dirt or on similar terrain where particles can get trapped in the fan. Do not use batteries if the magnets or connector pins are damaged.

### Offline maps

Skydio QGC requires a specific map file that can only be generated using the QGC application on a device with access to the Internet. To generate map files:

Step 1 - Using a computer or devices download the QGC application to your desktop

- http://qgroundcontrol.com/downloads
- Select Downloads
- Follow prompts
- Launch the QGC application
- Step 2 Select the QGC app menu in the top left corner
- Step 3 Select Settings
- Step 4 Select Offline Maps
- Step 5 Navigate to the Add New Set dialog box
- Step 6 Name your map set
- Step 7 Select the map type
  - · Zoom into a specific area to create your map
  - Set the zoom levels for offline maps
  - Select Download
  - Select the tile sets you want to export and select Export
- Step 8 copy the file with the extension .qgctiledb to a USB-C flash drive





### Offline maps

Import map to Skydio Enterprise Controller:

- Step 1 Power on your Skydio Enterprise Controller
- Step 2 Select the INFO menu
- Step 3 Select Import Skydio QGC Maps

 $\ensuremath{ \text{Step 4}}$  - Insert the USB-C flash drive containing the QGC map file

- Select Maps
- Navigate to My Files
- Select the USB storage device

- · Select the map file
- Select Done





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	Done			

### Offline maps

Your QGC map tiles will then import to the Skydio Enterprise Controller map directory.

After completing the final step, you will only have 24 seconds to import the maps to QGC before your map files are deleted.





**NOTE**: If an import fails, select and hold Import Skydio QGC Maps and clear the imported map directory when prompted. Any maps not yet imported to Skydio QGC will need to be imported again.

Import maps to QGC:

- Step 1 Select Open Skydio QGC
- Step 2 Select the QGC-Gov app icon
- Step 3 Select Settings
- Step 4 Select Offline Maps
  - Select Import and then Import again
  - Tap on the tile set to import
- Step 5 Select General menu
- Step 6 Scroll to the Miscellaneous tab
- Step 7 Choose the correct options from the Map Provider and Map Type menus
- Step 8 Navigate back to the Fly screen
  - · Ensure that your map provider and map types match



## QGC Flight

### Media Encryption

To provision the vehicle for encryption

Step 1 - Power on Skydio X2D

Step 2 - Insert the security key into the USB-C port on the vehicle

- The light on the key will begin blinking green
- Step 3 Remove the security key when the light on the security key turn off

When your vehicle is provisioned for encryption, your media will be encrypted when flying with Skydio QGC-Gov. The state of your media encryption in located in the status bar:



You have the option to enable or disable encryption. When Enable Encryption is selected, all media captured will be encrypted. When Disable Encryption is selected, all media captured will not be encrypted. To enable or disable encryption:

- Step 1 Power on your Skydio Enterprise Controller
  - Wait for your X2D to connect
- Step 2 Select the INFO menu
- Step 3 Select your drone under Paired Devices
- Step 4 Select Encryption
- Step 5 Enable (default) or Disable Encryption



### Global Settings Menu

The application menu provides access to:

- Fly (default) pilot both manually and autonomously, using map or camera view
- Plan missions, geofence, and rally points
- Vehicle Setup configure vehicle-specific settings (calibration)
- Settings configure user interface settings

### Settings

Configure settings:

Step 1 - Select the App Settings menu

Step 2 - Select General to set:

- Units of measure
- Language
- UI dark or light mode
- UI scaling
- Data persistence
- Telemetry logs
- Fly and plan view

Step 3 - Select Offline Maps to add a new map set

Step 4 - Select Console to view logs

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### Vehicle Setup

Use the Global Settings QGC menu to access the Vehicle Setup menu.

#### Step 1 - Select Fly Now

Step 2 - Select the II 🔍 QGC Global Settings icon

#### Step 3 - Select Vehicle Setup

- Summary
- Joystick
- Health
- Safety
- Parameters

### Summary

The Summary menu displays a overview of your settings selections.

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🚽 Summary	Below you will find a summ	ary of the settings for your ve	ehicle. To the left are the se	tup menus for each	i component.
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Health			Low Battery Failsafe RC Loss Failsafe RC Loss Timeout Data Link Loss Failsafe	Return at critical l	level, land at emergency level Return mode 0.5 s Return mode
Safety	Vehicle is Healthy		RTL Climb To RTL, Then Loiter Alt		65.6 ft Loiter and do not land 98.4 ft
Parameters					
	Airframe				
	System ID Airframe type Vehicle Firmware Version Custom Fw. Ver.	1 31.11.28rc 31ebc1cb9e359caf			

### Joystick Setup

- Step 1 Select the QGC Global Settings icon
- Step 2 Select Vehicle Setup
- Step 3 Select Joystick
- Step 4 Select the General tab

By default, flight controls are set to Mode 2, the left joystick controls the elevation and horizontal rotation of the drone, and the right joystick controls the forward, backward, and lateral movements of the drone.



### Joystick Button Assignment

You have the ability to modify the controller button mapping as needed. Button mapping in Skydio QGC will not change the button mapping in the Skydio Enterprise Controller.

- **Step 1** Select the QGC Global Settings icon
- Step 2 Select Vehicle Setup
- Step 3 Select Joystick
- Step 4 Select the Button Assignment tab

General				Button Assignment			Advanced
0 No Action	•	Repeat	1	Dismiss Prompts		Repeat	
2 Hold	•	Repeat	3	No Action		Repeat	
4 Thermal ON/OFF	•	Repeat	5	Trigger Camera / Video	•	Repeat	
6 Toggle Map / Video	•	Repeat	7	Takeoff / Land		Repeat	
8 No Action	•	Repeat	9	Toggle Obstacle Avoidance		Repeat	
10 Toggle Illumination Mode	•	Repeat	11	Toggle RTL		Repeat	

Pressing on each button on the controller will highlight the corresponding button number in the Skydio QGC, allowing you to verify your button assignments.

Button action	Behavior
NO ACTION	Button will not be mapped to any behavior
ARM	Starts autonomy engine and gets ready for takeoff
DISARM	Stops autonomy engine not ready for takeoff
TOGGLE ARM	Switch between the armed and disarmed states
CONTINUOUS ZOOM IN	Holding down the button will continue to zoom in
CONTINUOUS ZOOM OUT	Holding down the button will continue to zoom out
STEP ZOOM IN	A single zoom step is taken each button press

## Joystick Button Assignment

Button action	Behavior
STEP ZOOM OUT	A single zoom step is taken each button press
TRIGGER CAMERA	Captures a photo
TRIGGER VIDEO	Starts/stops recording
THERMAL ON/OFF	Toggle the thermal overly
THERMAL ON	Turn the thermal overlay on
THERMAL OFF	Turn the thermal overlay off
THERMAL NEXT PALETTE	Cycle between the thermal color palettes
TOGGLE OBSTACLE AVOIDANCE	Toggles obstacle avoidance settings Standard > Close/Reduced > Minimal > Disabled
TOGGLE RGB LEDs	Toggles RGB lights on/off
TOGGLE RTL	Initiate a return to launch (or rally point)
SENSOR SLEW	Reset the zoom level and center gimbal pitch
TOGGLE ILLUMINATION MODE	Switch between modes (none, visible strobe, IR strobe)
DISMISS PROMPTS	Dismiss any blocking prompts (required for night takeoff). Also cancel landing/takeoff
GIMBAL DOWN (FINE)	Pitch the gimbal up (scales with zoom)
GIMBAL UP (FINE)	Pitch the gimbal down (scales with zoom)
YAW LEFT (FINE)	Yaw the vehicle to the left (scales with zoom)
YAW RIGHT (FINE)	Yaw the vehicle to the right (scales with zoom)
LAND	Initiate a landing
TAKEOFF	Initiate a takeoff

### Joystick Advanced

You have the ability to modify the controller button mapping as needed. Button mapping in Skydio QGC will not change the button mapping in the Skydio Enterprise Controller.

- Step 1 Select the QGC Global Settings icon
- Step 2 Select Vehicle Setup
- Step 3 Select Joystick

#### Step 4 - Select the Advanced tab

- Full down stick is zero throttle (default) release joystick to center, the vehicle remains stationary
- Center stick is zero throttle manually fly/command an ascent to keep the vehicle at a stable altitude. Release joystick to center, the vehicle will descend
- Exponential slider control the joystick sensitivity ranging from 0 (full speed/sensitivity) --> .75 (least sensitive)

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	General	Button A	Assignme	ent				Adv	anced	
Soystick		Full down stick is	s zero thr	ottle						
Health		Center stick is ze	ero throttl	e						
Safety		Exponential:			0.39 ⇒					
Parameters										

### Health

The Health tab displays the status of flight performance.

#### Step 1 - Select the QGC Global Settings icon

#### Step 2 - Select Vehicle Setup

**Step 3** - Select **Health** - use this menu to view an overview of the vehicle, navigation, and flight readiness for your preflight check

- Green flight readiness
- Yellow unhealthy but not critical for flight
- Red unhealthy not ready for flight

UA Ready to Arm	Disarmed • 🔀 🍯 🏠	🗄 🔏 💷 🚦 53% 📢
UA Ready to Arm  Summary Summary Joystick Joystick Gyroscope Absolute Pressure Sensor Angular Rate Control X/Y Position Control Cogging Safety Parameters	Disarmed • Accelerometer GPS Attitude Stabilization Motor Outputs Battery	Magnetometer Vision Position Yaw Control AHRS Prearm Check

### Safety

The Safety tab displays the status of flight performance

- Step 1 Select the QGC Global Settings icon
- Step 2 Select Vehicle Setup
- Step 3 Select Safety use this menu to set the data loss link action from:

#### Return mode (default)

- The vehicle will return to the home point if the signal connection is lost
- Autonomous flight modes will stop
- Step 4 Set the Data Loss Link Timeout
  - Set the amount of time that you want the vehicle to wait before returning from 5 to 300 seconds

Step 5 - Set the return altitude from 0 (current altitude) to 492 (above current altitude) feet

#### Disabled

- The vehicle will continue the autonomous flight mode until the signal is reconnects or the battery is depleted
- The vehicle will land in place



### Launch Procedures

Step 1 - Find a clear area to launch

**Step 2** - Place X2D on a flat, stable surface

Select the Megaphone icon to display system notifications and status information for flight readiness. Dismiss this screen by tapping the X button in the top right corner.

- Step 3 Select Disarmed in the top toolbar
- Step 4 Slide to Arm the drone and start the Skydio Autonomy Engine
- **Step 5** Select the Takeoff button to begin the takeoff process
  - The propellers will begin to spin
  - The vehicle will launch



**WARNING:** Obstacle Avoidance is disabled during launch. The drone will launch, ascend and hover at 8 ft (2.4 m) above the ground, at which point Obstacle Avoidance is fully enabled. Exercise extreme care to avoid injury, and do not touch spinning propellers.





### Hand Launch Procedures

Step 1 - Identify a clear area to launch, 10 ft (3 m) above, 15 ft (4.5 m) in front, and 3 ft (1 m) on either side

- **Step 2** Do not hand launch on windy days. Ensure that it is not blowing towards you.
  - If the wind is gusty or coming from different directions, consider a ground launch
- Step 3 Create a launch pad on your open hand by lightly gripping the battery to stabilize
  - Keep the drone level and still, at arm's length from your body
  - Keep your fingers below the chassis and away from the propellers at all times
  - Point the camera away from you
  - Ensure that the rear propellers will not make contact with your arm

Initiate launch using:

Controlling device - select the launch button

Quick Launch - press the battery power button four times

Step 4 - As the propellers begin to spin up slowly relax your grip. Keep your hand still and level

- X2D will slide off your palm and take flight
- · Do not push or throw the vehicle up in the air

## Flight Screen



### Media Controls

Media controls to capture video and photos:

- Photo/Video icon allows you to toggle between video and photo mode
- Record/Shutter icon to start/stop recording or take still photos, depending on your capture mode
- · Settings icon to access the video/photo settings for both color and thermal camera

By default, Skydio X2D will not automatically record video or photos. Switch to your desired capture mode and tap the shutter button to record a video or take photos.

Select the Settings icon to adjust the video and photo settings for both the color and thermal cameras.

Select Video Settings to adjust exposure, video resolution, and thermal camera settings.

Restore Camera Defaults settings to default select Reset

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Plan Takeoff Return Set Home Action		Video Settings Color Stream Bitrate Control Exposure Mode Exposure Compensation Video Resolution Thermal Stream Bitrate	Auto         0           1920 x 1080 30fps	• • • •	×	El Camera Module 231 90 GB Valo 144 Settings 600200	<u>фа</u> П П П П
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Choose between the three different views and the thermal camera palette options.

From left to right:

- Color Camera
- Picture in Picture
- Thermal Camera
- Thermal Camera Palette





### Flight Information Bar

The **Flight Information** menu displays live flight telemetry from Skydio X2.



Double-tap the **Flight Information** to display a limited menu for more space to view the map or live video.

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**NOTE:** No GPS indicates the Skydio Enterprise Controller does not have a GPS position. This is normal.

### Status Bar

The Status Bar menu offers more information about the status and health of Skydio X2D





### Home Point

- Step 1 Select the Home tab
- Step 2 Press and hold anywhere on the map
  - Home point location represented by an H on the map
- Step 3 Select the altitude
- Step 4 Select the Home icon on the left side of the screen
- Step 5 Slide to confirm



### Map View

 Image: Control (Control (Contro) (Control (Control (Control (C

The view in the bottom left of the screen displays the map.

Tap the Map picture-in-picture (PIP) to view the Map full screen and minimize the video stream. Tap the video stream in the bottom left corner again to make the video stream full screen and minimize the Map. Tap and drag the corner of the PIP to increase or decrease its size. Pinch with two fingers to zoom in on the map. Pinch out with two fingers to zoom out of the map. With one finger, drag on the map to move the map around.

## Home Point

- Step 1 Select the Home tab
- Step 2 Press and hold anywhere on the map
  - Home point location represented by an H on the map
- Step 3 Select the altitude



Step 4 - To return to the home point select the Home icon on the left side of the screen

Slide to confirm

### Waypoint Mission

Missions allow X10D to fly to designated waypoints without requiring you to manually fly. As the vehicle reaches each waypoint, it can execute preset operations before proceeding to the next waypoint. Missions can be planned preflight.

- Step 1 Select the Plan button to display the Map view
- Step 2 Select the parameters to set X2D behaviors while executing a mission

Step 3 - Select the Waypoint button to begin marking waypoints

- Tap on the map to set the waypoints
- · Continue tapping on the map to set waypoints until your mission plan is complete

Step 4 - Adjust parameters and behaviors in the right sidebar, such as:

- Altitude
- Hold duration (in seconds)
- Will loiter before proceeding
- Change the gimbal pitch angle
- Planned photo





Select the **hamburger** icon to set a different command for that waypoint in the mission. To delete a waypoint select the waypoint and the trash can

Insert waypoint
Insert pattern
Delete
Move to vehicle position
Move to previous item position
Edit position
Show all values

Plan

### Waypoint Mission

**Step 5 -** Select **Upload Required** to upload the mission. A notification will display if the mission upload is successful.

Return to the flight screen and begin the mission by sliding from left to right on Slide to confirm.



**Upload Required** 



**II** Pause

While a mission is executing, tap the Pause button in the left Toolbar and slide from left to right on Slide to confirm to pause the mission.

Slide from left to right again to resume the mission.



### Orbit a point of interest

Step 1 - Press and hold anywhere on the map to set the orbit point

#### Step 2 - Slide to confirm

· Adjust the orbit range by adjusting the vehicle's pitch while in flight





## **II** Pause

While a orbit is executing, tap the Pause button in the left Toolbar to stop the vehicle at its current location. Slide to confirm.



### Track

To initiate a subject track

- Step 1 Select the subject detection icon to enabled in EO or IR
- Step 2 -Locate a point of interest on the map view



- Step 4 Adjust the orbit range by adjusting the vehicle's pitch while in flight
- Step 5 Select Clear POI to stop tracking



EO

### GPS Night Flight

Enable GPS Night Flight when flying in low-light conditions. Obstacle Avoidance is disabled, the vehicle will use GPS sensors, instead of its vision system, to navigate. Skydio X2 will notify you in QGC if the environment is too dark to fly using the vision navigation system and will prompt you to fly using GPS Night Flight.

Step 1 - Disable obstacle avoidance

**Step 2** - Select the **C2** button to enable infrared or strobe light



#### **Obstacle avoidance**

When flying at night, Skydio X2 does not use the vision system and **obstacle avoidance is disabled**. Take extra caution when piloting the drone to avoid obstacles and stay clear of people.

#### Visibility

Improve visibility by enabling X2 infrared or visible strobe lights.

#### **Return behavior**

When returning, Skydio X2 will first ascend 65 ft (20 m) before returning. Once it has arrived at the rally point, it will descend to 35 ft (10 m) AGL (above ground level). Skydio X2 does not avoid obstacles when in GPS Night Flight mode, so keep the return behavior in mind before commanding a return. When landing, use the controller joystick to descend down to **15 ft (3 m)** then once you're ready to land, press and hold the **LAND** button on the screen or the controller.



**WARNING:** GPS Night Flight mode requires flying without obstacle avoidance. X2 may drift when in GPS Night Flight mode; take extra caution when flying in this mode and do not stand near the vehicle. Never hand launch or land Skydio X2 when flying at night.

## GPS Night Flight

If this is your first time enabling GPS Night Flight mode, you will need to complete a calibration before flight. Access the calibration modes in the Vehicle Setup menu.

#### Hand Wave:

Toggle Hand Wave calibration on

- select the Settings menu and the Drone tab
- select GPS Night Flight
- enable GPS Night Flight Mode
- wave the drone back-and-forth



A visual tutorial will guide you through the calibration process the first time you initiate a Hand Wave Calibration. Access the instructions at any time by navigating to the info menu and selecting Hand Wave Guide.



**NOTE:** Calibration will not be required for several weeks or even months, depending on the environment. You will be prompted when another calibration is necessary.

### Land

When you are ready to land:

- Step 1 Descend down to 15 ft (3 m)
- Step 2 Select the Land button
- **Step 3 -** Confirm the land action by sliding from left to right when prompted.



Land

### Exit QGC-Gov

- Step 1 Disarm your Skydio X2D
- Step 2 Select the QGC icon
- Step 3 Select Home
- Step 4 Select Yes to confirm
  - To return to the Home Screen
  - The signal link will disconnect momentarily





Control #: A0156